

Help message for MATLAB function *refval.m*

```
>> help refval
Function refval determines the geometric and physical constants of the
equipotential rotational reference ellipsoid of the Geodetic Reference
System 1980 (GRS80) defined by:
    a - semi-major axis,
    GM - geocentric gravitational constant of the Earth,
    J2 - dynamical form factor and
    omega - angular velocity of the Earth

For GRS80 the defining parameters are
    a = 6378137 m
    GM = 3.986005e+14 m^3/s^2
    J2 = 1.08263e-03
    omega = 7.292115e-05 rad/s
```

Output from MATLAB function *refval.m*

```
>> refval

GEODETTIC REFERENCE SYSTEM 1980
=====
Defining Constants (exact)

    a = 6378137.000 m          semi-major axis
    GM = 3.986005e+14 m^3/s^2 geocentric gravitational constant
    J2 = 1.082630e-03         dynamical form factor
    omega = 7.292115e-05 rad/s angular velocity

Derived Geometrical Constants of Normal Ellipsoid

    b = 6356752.314140 m      semi-minor axis
    E = 521854.009700 m      linear eccentricity
    c = 6399593.625864 m      polar radius of curvature
    e2 = 6.694380022903e-03    eccentricity squared
    ep2 = 6.739496775482e-03    2nd eccentricity squared
    f = 3.352810681184e-03     flattening
    flat = 298.257222100882     denominator of flattening
    n = 1.679220394629e-03     3rd flattening
    Q = 10001965.729230 m      quadrant distance
    R1 = 6371008.771380 m      mean radius R1 = (2a+b)/3
    R2 = 6371007.180884 m      radius of sphere of same surface area
    R3 = 6371000.789974 m      radius of sphere of same volume

Derived Physical Constants of Normal Ellipsoid

    U0 = 62636860.850046 m^2/s^2 normal gravity potential
    J4 = -2.370912218650e-06    spherical-harmonic coefficient
    J6 = +6.083470628388e-09    spherical-harmonic coefficient
    J8 = -1.426814059713e-11    spherical-harmonic coefficient
    m = 3.449786003078e-03
    g_e = 9.780326771534 m/s^2   normal gravity at equator
    g_p = 9.832186368521 m/s^2   normal gravity at pole
    f* = 0.005302440113         gravity flattening
    k = 0.001931851353          constant in Pizzetti's equation

>>
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MATLAB function refval.m

```
function refval
% Function refval determines the geometric and physical constants of the
% equipotential rotational reference ellipsoid of the Geodetic Reference
% System 1980 (GRS80) defined by:
%
%       a - semi-major axis,
%       GM - geocentric gravitational constant of the Earth,
%       J2 - dynamical form factor and
%       omega - angular velocity of the Earth
%
% For GRS80 the defining parameters are
%       a = 6378137 m
%       GM = 3.986005e+14 m^3/s^2
%       J2 = 1.08263e-03
%       omega = 7.292115e-05 rad/s

%=====
% Function: refval
%
% Usage:   refval;
%
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%   RMIT University,
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%   AUSTRALIA
%   email: rod.deakin@rmit.edu.au
%
% Date:
%   Version 2   21 May 2014
%
% Note that Version 1 was written as a C++ program in June 1996 with
% revisions in December 1996 and June 1997.
%
% Functions Required:
%   None
%
% Remarks:
%   Function refval() determines the geometric and physical constants of the
%   equipotential rotational reference ellipsoid defined by:
%
%       a       - semi-major axis,
%       GM      - geocentric gravitational constant of the Earth,
%       J2      - dynamical form factor and
%       omega   - angular velocity of the Earth.
%
%   Given the four defining parameters above, geometric and physical
%   constants can be derived by methods and formulae set out in Ref[1].
%   Theory is given in Ref[2] and Ref[4] and a FORTRAN program listing is
%   given in Ref[3].
%   e2 (first eccentricity squared) is the fundamental derived constant from
%   which the other geometric constants can be computed. Ref[1] and Ref[4]
%   show how e2 is linked to a, GM, J2 and omega via the formulae
%
%       
$$e2 = 3J2 + (\omega^2)*(a^3)/GM * 4/15*(e^3)/2q0$$

%
%   This equation must be solved iteratively since e appears on both sides
%   of the equal sign. A summation formula for  $2q0/(e^3)$  can be derived by
%   considering the equations given in Ref[1] p.398. Also see ref[4],
%   eq(73), p.28.
%
%   The following geometric constants of the ellipsoid are evaluated
%
%   b       - semi-minor axis of ellipsoid (metres)
%   c       - polar radius of curvature (metres)
%   ep2     - second eccentricity squared:  $ep = E/b$ 
%   E       - linear eccentricity:  $E = \sqrt{a^2 - b^2} = a*e$ 
%   f       - flattening of ellipsoid
%   flat    - denominator of flattening:  $f = 1/flat$ 
%   n       - third flattening of ellipsoid:  $n = f/(2-f)$ 
%   Q       - quadrant distance of ellipsoid (metres)
%   R1      - radius of sphere having mean radius:  $R1 = (2*a + b)/3$ 
%   R2      - radius of sphere having same surface area of ellipsoid
%   R3      - radius of sphere having same volume of ellipsoid
%
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% The following physical constants of the ellipsoid are evaluated
% gamma_e - normal gravity at equator (m/s^2)
% gamma_p - normal gravity at pole (m/s^2)
% J4,J6,J8,... - coefficients of Legendre polynomials in the spherical
%               harmonic expansion of the gravitational potential V.
% k           - constant in Pizetti's equation for normal gravity.
% m           - a derived physical constant:  $m = \omega^2 a^2 b / GM$ 
% q0          -  $q(\text{subscript zero})$ , physical constant used in computation of
%               gamma_e, gamma_p
% qp0         -  $q\text{-primed}(\text{subscript zero})$ , physical constant used in
%               computation of gamma_e, gamma_p
% U0          - normal gravity potential at ellipsoid ( $m^2/s^2$ )
%
% Variables:
% a           - semi-major axis of ellipsoid (metres)
% b           - semi-minor axis of ellipsoid (metres)
% c           - polar radius of curvature (metres)
% c0          - coefficient in computation of quadrant distance Q
% e           - (first) eccentricity of ellipsoid:  $e = E/a$ 
% e2          - (first) eccentricity squared
% e21         - approximate value of e2
% ep          - second eccentricity:  $ep = E/b$ 
% ep2         - second eccentricity squared
% E           - linear eccentricity:  $E = \sqrt{a^2 - b^2} = a*e$ 
% f           - flattening of ellipsoid:  $f = (a-b)/a = 1-\sqrt{1-e^2}$ 
% f1          - gravity flattening
% flat        - denominator of flattening:  $f = 1/flat$ 
% gamma_e     - normal gravity at equator (m/s^2)
% gamma_p     - normal gravity at pole (m/s^2)
% GM          - geocentric gravitational constant ( $m^3/s^2$ )
% i,j         - integer counters
% Jvec        - vector of zonal harmonic terms for computation of normal
%               gravitational potential V
% J2          - dynamical form factor
% k           - constant in Pizetti's equation for normal gravity.
% m           - a derived physical constant:  $m = \omega^2 a^2 b / GM = m1/a*b$ ;
% m1          - a derived physical constant:  $m1 = \omega^2 a^3 / GM = m/b*a$ ;
% n           - third flattening of ellipsoid:  $n = f/(2-f)$ 
% n2,n4,...   - even powers of n
% N           - size of vector Jvec
% omega       - angular velocity of earth (radians/sec)
% q0          -  $q(\text{subscript zero})$ , physical constant used in computation of
%               gamma_e, gamma_p
% qp0         -  $q\text{-primed}(\text{subscript zero})$ , physical constant used in
%               computation of gamma_e, gamma_p
% Q           - quadrant distance of ellipsoid (metres)
% R1          - radius of sphere having mean radius:  $R1 = (2*a + b)/3$ 
% R2          - radius of sphere having same surface area as ellipsoid
% R3          - radius of sphere having same volume as ellipsoid
% sgn         -  $sgn = 1$  or  $sgn = -1$ 
% U0          - normal gravity potential at ellipsoid ( $m^2/s^2$ )
% x           - local variable
%
% References:
% 1. Moritz, H., 1980, 'Geodetic Reference System 1980', Bulletin
%    Geodesique Vol.54(3), 1980, pp.395-405.
% 2. Heiskanen, W.A. and Moritz, H. (1967). Physical Geodesy, W.H.Freeman
%    and Co., London, 364 pages.
% 3. Tscherning, C.C., Rapp, R.H. and Goad C., (1983). 'A Comparison of
%    methods for Computing Gravimetric Quantities from High Degree
%    Spherical Harmonic Expansions', Manuscripta Geodaetica, Vol.8,
%    1983, p.249-272.
% 4. Deakin, R.E., 1997. 'The Normal Gravity Field', Private Notes,
%    Department of Geospatial Science, RMIT University, 38 pages.
% 5. Deakin, R.E. & Hunter, M.N., 2012. 'A Fresh Look at the UTM
%    Projection: Karney-Krueger equations', Presented at the Surveying
%    and Spatial Sciences Institute (SSSI) Land Surveying Commission
%    National Conference, Melbourne, 18-21 April, 2012.
% 6. Deakin, R.E. & Hunter, M.N., 2013. 'Geometric Geodesy Part A', School
%    of Mathematical & Geospatial Sciences, RMIT University, 3rd
%    printing, January 2013.
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%-----
% set defining constants of rotational equipotential ellipsoid for GRS80
%-----
a = 6378137.0;
GM = 3.986005e+14;
J2 = 1.08263e-03;
omega = 7.292115e-05;

%-----
% compute e2 (first eccentricity squared)
%-----
% See Ref[1], p.398
% set initial value of first eccentricity squared
m1 = omega^2*a^3/GM;
e21 = 3*J2 + m1;
% set e2 = initial value
e2 = e21;
for i = 1:10
    ep2 = e2/(1-e2);
    x = (1/(1-e2))^(3/2);
    sgn = 1;
    twoq0 = 0;
    % this loop calculates 2q0/(e^3)
    for j = 1:20
        twoq0 = twoq0 + (sgn*(4*j/(2*j+1)/(2*j+3)*x));
        sgn = -sgn;
        x = x*ep2;
    end
    % set e2 = initial value + correction
    e2 = e21 + (m1*((4/15/twoq0)-1));
end
% e2 now known, calculate geometric constants of ellipsoid

%-----
% compute GEOMETRIC constants of equipotential ellipsoid
%-----
e = sqrt(e2); % eccentricity of ellipsoid
ep2 = e2/(1-e2); % 2nd eccentricity squared
ep = sqrt(ep2); % 2nd eccentricity
f = 1 - sqrt(1-e2); % flattening
flat = 1/f; % denominator of flattening
b = a*(1-f); % semi-minor axis of ellipsoid
E = a*e; % linear eccentricity
c = a*a/b; % polar radius of curvature
n = f/(2-f); % 3rd flattening

% computation of quadrant length of ellipsoid. See Ref[5], eq (39).
n2 = n*n; % even powers of n
n4 = n2*n2;
n6 = n4*n2;
n8 = n6*n2;
c0 = 1 + 1/4*n2 + 1/64*n4 + 1/256*n6 + 25/16384*n8;
Q = a/(1+n)*c0*(pi/2); % quadrant distance

% computation of radii of equivalent spheres. See Ref[6], pp. 86-87.
R1 = (2*a+b)/3;
R2 = sqrt(a^2/2*(1+(1-e2)/(2*e)*log((1+e)/(1-e))));
R3 = (a^2*b)^(1/3);

%-----
% compute PHYSICAL constants of equipotential ellipsoid
%-----

% compute normal potential of the reference ellipsoid U0
% See Ref[1] pp.399-400, Ref[2] p.67, eq.(2-61), Ref[4] eq.(38b)
U0 = GM/E*atan(ep) + omega^2*a^2/3;

% compute normal gravity at equator and poles
% formula for q0 given in Ref[2] eq.(2-58), p.66 and Ref[4] eq.(31), p.12
% see also Ref[1] p.398
q0 = ((1+(3/ep2))*atan(ep)-(3/ep))/2;
% formula for qp0 given in Ref[2] eq.(2-67), p.68 and Ref[4] eq.(52), p.19
% see also Ref[1] p.400; Ref[4] eq.(52)
qp0 = 3*(1+(1/ep2))*(1-(1/ep*atan(ep))) - 1;

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% compute normal gravity at the equator and the pole
% formulae for gamma_e and gamma_p given in Ref[2] eqs (2-73) and (2-74),
% p.69; Ref[1] p.400 and Ref[4], eqs (62a),(62b).
m = m1/a*b;
gamma_e = GM/a/b*(1-m-(m/6*ep*qp0/q0));
gamma_p = GM/a/a*(1+(m/3*ep*qp0/q0));
% compute gravity flattening
f1 = gamma_p/gamma_e - 1;
% compute constant k in Pizetti's equation for normal gravity
% formula for k in Ref[1], p.401 and Ref[4] eq.(68), p.26.
k = b*gamma_p/(a*gamma_e) - 1;

%---compute the coefficients J4, J6, J8, ... J20
% set dimensions of vector Jvec()
N = 20;
Jvec = zeros(N,1);
% This vector is used store the coeff's J2, J4, J6, ... J20 where J(2n) are
% related to J2. See Ref[2], p.73, eqs. (2-92),(2-92') and Ref[4] eq.(86)
% Also Jvec(1,1) = Jvec(3,1) = Jvec(5,1) = ... = Jvec(odd,1) = 0.
% The elements of Jvec() are used in computations of the normal potential V
% and its derivatives. Note also that the elements of Jvec() are zonal
% terms, i.e. the order is zero (m=0) thus they are also equal to quasi-
% normalised coefficients. See Ref[3], eq. 21, p. 258.

% set value of Jvec(2,1)
Jvec(2,1) = J2;
% set even values of Jvec() */
for j=2:N/2
    sgn = (-1)^(j+1);
    x1 = 3/(2*j+1)/(2*j+3)*e2^j;
    x2 = 1 - j + (5*j*J2/e2);
    Jvec(2*j,1) = sgn * x1 * x2;
end

% print headings and computed data
fprintf('\n\nGEODETTIC REFERENCE SYSTEM 1980');
fprintf('\n=====');
fprintf('\nDefining Constants (exact) \n');
fprintf('\n    a = %12.3f m          semi-major axis',a);
fprintf('\n    GM = %9.6e m^3/s^2    geocentric gravitational constant',GM);
fprintf('\n    J2 = %9.6e           dynamical form factor',J2);
fprintf('\n    omega = %9.6e rad/s    angular velocity',omega);

fprintf('\n\nDerived Geometrical Constants of Normal Ellipsoid \n');
fprintf('\n    b = %15.6f m          semi-minor axis',b);
fprintf('\n    E = %15.6f m          linear eccentricity',E);
fprintf('\n    c = %15.6f m          polar radius of curvature',c);
fprintf('\n    e2 = %15.12e          eccentricity squared',e2);
fprintf('\n    ep2 = %15.12e         2nd eccentricity squared',ep2);
fprintf('\n    f = %15.12e           flattening',f);
fprintf('\n    flat = %15.12f        denominator of flattening',flat);
fprintf('\n    n = %15.12e           3rd flattening',n);
fprintf('\n    Q = %15.6f m          quadrant distance',Q);
fprintf('\n    R1 = %15.6f m         mean radius R1 = (2a+b)/3',R1);
fprintf('\n    R2 = %15.6f m         radius of sphere of same surface area',R2);
fprintf('\n    R3 = %15.6f m         radius of sphere of same volume',R3);

fprintf('\n\nDerived Physical Constants of Normal Ellipsoid \n');
fprintf('\n    U0 = %15.6f m^2/s^2 normal gravity potential',U0);
fprintf('\n    J4 = %15.12e          spherical-harmonic coefficient',Jvec(4));
fprintf('\n    J6 = %15.12e          spherical-harmonic coefficient',Jvec(6));
fprintf('\n    J8 = %15.12e          spherical-harmonic coefficient',Jvec(8));
fprintf('\n    m = %15.12e           m');
fprintf('\n    g_e = %15.12f m/s^2    normal gravity at equator',gamma_e);
fprintf('\n    g_p = %15.12f m/s^2    normal gravity at pole',gamma_p);
fprintf('\n    f* = %15.12f          gravity flattening',f1);
fprintf('\n    k = %15.12f           constant in Pizzetti's equation',k);

fprintf('\n\n');

```